Parallel Databases and Map Reduce

Introduction to Databases
CompSci 316 Spring 2017
Announcements (Wed., Apr. 17)

• Homework #4 due Monday, April 24, 11:55 pm
  • No other extra credit problem

• Project Presentations
  • A few project groups still have not signed up – please sign up soon

• Google Cloud code
  • Please redeem your code asap, by May 11

• Wednesday April 19
  • Guest Lecture by Prof. Jun Yang
  • OLAP, Data warehousing, Data mining
  • Included in the final
Where are we now?

We learnt

✓ Relational Model, Query Languages, and Database Design
  ✓ SQL
  ✓ RA
  ✓ E/R diagram
  ✓ Normalization

✓ DBMS Internals
  ✓ Storage
  ✓ Indexing
  ✓ Query Evaluation
  ✓ External sort
  ✓ Join Algorithms
  ✓ Query Optimization

✓ Transactions
  ✓ Basic concepts and SQL
  ✓ Concurrency control
  ✓ Recovery

✓ XML
  ✓ DTD and XML schema
  ✓ XPath and XQuery
  ✓ Relational Mapping

Next
  • Parallel DBMS
  • Map Reduce
  • Data Warehousing, OLAP, mining
  • Distributed DBMS
  • NOSQL

Today

Wednesday

Next Monday
Parallel DBMS
Why Parallel Access To Data?

At 10 MB/s
1.2 days to scan

1,000 x parallel
1.5 minute to scan.

Parallelism:
divide a big problem into many smaller ones to be solved in parallel.
Parallel DBMS

- Parallelism is natural to DBMS processing
  - Pipeline parallelism: many machines each doing one step in a multi-step process.
  - Data-partitioned parallelism: many machines doing the same thing to different pieces of data.
  - Both are natural in DBMS!

Pipeline

Partition

outputs split N ways, inputs merge M ways
DBMS: The parallel Success Story

• DBMSs are the most successful application of parallelism
  • Teradata (1979), Tandem (1974, later acquired by HP),..
  • Every major DBMS vendor has some parallel server

• Reasons for success:
  • Bulk-processing (= partition parallelism)
  • Natural pipelining
  • Inexpensive hardware can do the trick
  • Users/app-programmers don’t need to think in parallel
Some || Terminology

**Ideal graphs**

**Speed-Up**
- More resources means proportionally less time for given amount of data.

**Scale-Up**
- If resources increased in proportion to increase in data size, time is constant.
Some || Terminology

In practice

• Due to overhead in parallel processing

• Start-up cost

Starting the operation on many processor, might need to distribute data

• Interference

Different processors may compete for the same resources

• Skew

The slowest processor (e.g. with a huge fraction of data) may become the bottleneck
Architecture for Parallel DBMS

• Units: a collection of processors
  • assume always have local cache
  • may or may not have local memory or disk (next)

• A communication facility to pass information among processors
  • a shared bus or a switch

• Among different computing units
  • Whether memory is shared
  • Whether disk is shared
Shared Memory

- Easy to program
- Expensive to build
- Low communication overhead: shared memory
- Difficult to scaleup (memory contention)

Diagram:
- Interconnection Network
- Global Shared Memory
  - P: Processor
  - D: Device

Example: SMP Server
Shared Nothing

- Hard to program and design parallel algos
- Cheap to build
- Easy to scaleup and speedup
- Considered to be the best architecture

local memory and disk

no two CPU can access the same storage area

all communication through a network connection

Interconnection Network

P

M

D

P

M

D

P

M

D

e.g. Greenplum
Shared Disk

- Trade-off but still interference like shared-memory (contention of memory and nw bandwidth)

Interconnection Network

e.g. ORACLE RAC
Different Types of DBMS Parallelism

- Intra-operator parallelism
  - get all machines working to compute a given operation (scan, sort, join)
  - OLAP (decision support)

- Inter-operator parallelism
  - each operator may run concurrently on a different site (exploits pipelining)
  - For both OLAP and OLTP (transaction)

- Inter-query parallelism
  - different queries run on different sites
  - For OLTP

- We’ll focus on intra-operator parallelism

Ack:
Slide by Prof. Dan Suciu
Data Partitioning

Horizontally Partitioning a table (why horizontal?):

**Range-partition**
- Good for equijoins, range queries, group-by
- Can lead to data skew

**Hash-partition**
- Good for equijoins
- But only if hashed on that attribute
- Can lead to data skew

**Block-partition or Round Robin**
- Send $i$-th tuple to $i \mod n$ processor
- Good to spread load
- Good when the entire relation is accessed

Shared disk and memory less sensitive to partitioning, Shared nothing benefits from "good" partitioning
Example

• $R(\text{Key}, A, B)$

• Can Block-partition be skewed?
  • no, uniform

• Can Hash-partition be skewed?
  • on the key: uniform with a good hash function
  • on $A$: may be skewed,
    • e.g. when all tuples have the same $A$-value
Parallelizing Sequential Evaluation Code

• “Streams” from different disks or the output of other operators
  • are “merged” as needed as input to some operator
  • are “split” as needed for subsequent parallel processing

• Different Split and merge operations appear in addition to relational operators

• No fixed formula for conversion

• Next: parallelizing individual operations
Parallel Scans

• Scan in parallel, and merge.
• Selection may not require all sites for range or hash partitioning
  • but may lead to skew
  • Suppose $\sigma_A = 10 R$ and partitioned according to A
    • Then all tuples in the same partition/processor
• Indexes can be built at each partition
Parallel Sorting

Idea:

• Scan in parallel, and range-partition as you go
  • e.g. salary between 10 to 210, #processors = 20
  • salary in first processor: 10-20, second: 21-30, third: 31-40, ....

• As tuples come in, begin “local” sorting on each
• Resulting data is sorted, and range-partitioned
• Visit the processors in order to get a full sorted order
• Problem: skew!
• Solution: “sample” the data at start to determine partition points.
Parallel Joins

• Need to send the tuples that will join to the same machine
  • also for GROUP-BY

• Nested loop:
  • Each outer tuple must be compared with each inner tuple that might join
  • Easy for range partitioning on join cols, hard otherwise

• Sort-Merge:
  • Sorting gives range-partitioning
  • Merging partitioned tables is local
Parallel Hash Join

• In first phase, partitions get distributed to different sites:
  • A good hash function *automatically* distributes work evenly
• Do second phase at each site.
• Almost always the winner for equi-join
Dataflow Network for parallel Join

- Good use of split/merge makes it easier to build parallel versions of sequential join code.
Parallel Aggregates

• For each aggregate function, need a decomposition:
  • count(S) = \( \sum \text{count}(s(i)) \), ditto for sum()
  • avg(S) = (\( \sum \text{sum}(s(i)) \)) / \( \sum \text{count}(s(i)) \)
  • and so on...

• For group-by:
  • Sub-aggregate groups close to the source.
  • Pass each sub-aggregate to its group’s site.
    • Chosen via a hash fn.

Which SQL aggregate operators are not good for parallel execution?
Best serial plan may not be best

Why?

Trivial counter-example:
- Table partitioned with local secondary index at two nodes
- Range query: all of node 1 and 1% of node 2.
- Node 1 should do a scan of its partition.
- Node 2 should use secondary index.
Example problem: Parallel DBMS

R(a,b) is horizontally partitioned across N = 3 machines.

Each machine locally stores approximately 1/N of the tuples in R.

The tuples are randomly organized across machines (i.e., R is block partitioned across machines).

Show a RA plan for this query and how it will be executed across the N = 3 machines.

Pick an efficient plan that leverages the parallelism as much as possible.

- SELECT a, max(b) as topb
- FROM R
- WHERE a > 0
- GROUP BY a
R(a, b)

Machine 1
1/3 of R

Machine 2
1/3 of R

Machine 3
1/3 of R

SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
R(a, b)

```
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```

If more than one relation on a machine, then “scan S”, “scan R” etc
\[ \text{R(a, b)} \]

\[
\begin{align*}
\sigma_{a>0} & \quad \text{scan} \\
\text{Machine 1} & \quad 1/3 \text{ of } R \\
\sigma_{a>0} & \quad \text{scan} \\
\text{Machine 2} & \quad 1/3 \text{ of } R \\
\sigma_{a>0} & \quad \text{scan} \\
\text{Machine 3} & \quad 1/3 \text{ of } R \\
\end{align*}
\]

\[
\text{SELECT a, max(b) as topb FROM R WHERE a > 0 GROUP BY a}
\]
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a

R(a, b)
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a

Machine 1

Machine 2

Machine 3
Same Example Problem: Map Reduce

Explain how the query will be executed in MapReduce (recall Lecture-3)

- SELECT a, max(b) as topb
- FROM R
- WHERE a > 0
- GROUP BY a

Specify the computation performed in the map and the reduce functions
Map

• Each map task
  • Scans a block of R
  • Calls the map function for each tuple
  • The map function applies the selection predicate to the tuple
  • For each tuple satisfying the selection, it outputs a record with key = a and value = b

```sql
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```

When each map task scans multiple relations, it needs to output something like

**key = a and value = (‘R’, b)**

which has the relation name ‘R’
Shuffle

• The MapReduce engine reshuffles the output of the map phase and groups it on the intermediate key, i.e. the attribute a

SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
Reduce

• Each reduce task
  • computes the aggregate value \( \text{max}(b) = \text{topb} \) for each group (i.e. \( a \)) assigned to it (by calling the reduce function)
  • outputs the final results: \((a, \text{topb})\)

A local combiner can be used to compute local max before data gets reshuffled (in the map tasks)

• Multiple aggregates can be output by the reduce phase like key = \( a \) and value = \((\text{sum}(b), \text{min}(b))\) etc.

• Sometimes a second (third etc) level of Map-Reduce phase might be needed

```
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```
Benefit of hash-partitioning

• What would change if we hash-partitioned R on R.a before executing the same query on the previous parallel DBMS

```
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a

Prev: block-partition

\[ \gamma_{a, \max(b)} \rightarrow \text{topb} \]

\[ \text{Hash on } a \]

\[ \sigma_{a > 0} \]

\[ \text{scan} \]

Machine 1

\[ \frac{1}{3} \text{ of } R \]
• It would avoid the data re-shuffling phase
• It would compute the aggregates locally

SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
Hash-partition on a for R(a, b)

SELECT a, max(b) as topb
WHERE a > 0
GROUP BY a

FROM R

g_a, max(b) -> topb
σ_{a>0}
scan
Machine 1
1/3 of R
Map Reduce
Big Data

- it cannot be stored in one machine
  - store the data sets on multiple machines
    - e.g. Google File System
      - SOSP 2003

- it cannot be processed in one machine
  - parallelize computation on multiple machines
    - e.g. MapReduce
      - OSDI 2004
Where does Google use MapReduce?

Input:
- crawled documents
- web request logs

MapReduce:
- inverted indices
- graph structure of web documents
- summaries of the number of pages crawled per host
- the set of most frequent queries in a day

Output:
What is MapReduce?

It is a programming model that processes large data by:
apply a function to each logical record in the input (map)
categorize and combine the intermediate results into summary values (reduce)
Google’s MapReduce is inspired by map and reduce functions in functional programming languages.
For example, in Scala functional programming language,

```scala
scala> val lst = List(1,2,3,4,5)
scala> lst.map( x => x + 1 )
res0: List[Int] = List(2,3,4,5,6)
```
For example, in Scala functional programming language,

```scala
scala> val lst = List(1,2,3,4,5)
scala> lst.reduce((a, b) => a + b)
res0: Int = 15
```
Ok, it makes sense in one machine.

Then, how does Google extend the functional idea to multiple machines in order to process large data?
Understanding MapReduce
(by example)
I am a class president
An English teacher asks you:
“Could you count the number of occurrences of each word in this book?”
Um… Ok…
Let’s divide the workload among classmates.
And let few combine the intermediate results

I will collect from A ~ G

A: 11
B: 9
... 
G: 14

H ~ Q

A: 6
B: 2
... 
G: 12

H: 8
... 
Q: 1

R ~ Z

R: 6
... 
Z: 2
Why did MapReduce become so popular?
Is it because Google uses it?
Distributed Computation
Before MapReduce

Things to consider:

• how to divide the workload among multiple machines?
• how to distribute data and program to other machines?
• how to schedule tasks?
• what happens if a task fails while running?
• ... and ... and ...
Distributed Computation
After MapReduce

Things to consider:

• how to write Map function?
• how to write Reduce function?
MapReduce lowered the knowledge barrier in distributed computation.

Developers needed before MapReduce

Developers needed after MapReduce
Map-Reduce Steps

- Input is typically (key, value) pairs
  - but could be objects of any type
- Map and Reduce are performed by a number of processes
  - physically located in some processors
Map-Reduce Steps

1. Read Data
2. Map – extract some info of interest in (key, value) form
3. Shuffle and sort
   - send same keys to the same reduce process
4. Reduce
   - operate on the values of the same key
   - e.g. transform, aggregate, summarize, filter
5. Output the results (key, final-result)
Simple Example: Map-Reduce

- Word counting
- Inverted indexes

Ack:
Slide by Prof. Shivnath Babu
Each map process works on a chunk of data -- master selects available workers

Input: (input-key, value)

Output: (intermediate-key, value) -- may not be the same as input key value

Example: list all doc ids containing a word
  - output of map (word, docid) – emits each such pair
  - word is key, docid is value
  - duplicate elimination can be done at the reduce phase
Reduce Function

- **Input**: (intermediate-key, list-of-values-for-this-key) – list can include duplicates
  - each map process can leave its output in the local disk, reduce process can retrieve its portion
  - master selects idle workers for reduce
- **Output**: (output-key, final-value)
- **Example**: list all doc ids containing a word
  - output will be a list of (word, [doc-id1, doc-id5, ...])
  - if the count is needed, reduce counts #docs, output will be a list of (word, count)
Key Players in MapReduce

• A Map-Reduce “Job”
  • e.g. count the words in all docs
  • complex queries can have multiple MR jobs
• Map or Reduce “Tasks”
  • A group of map or reduce “functions”
  • scheduled on a single “worker”
• Worker
  • a process that executes one task at a time
  • one per processor, so 4-8 per machine
  • Follows whatever the Master asks to do
• One Master
  • coordinates many workers.
  • assigns a task to each worker
Fault Tolerance

Although the probability of a machine failure is low, the probability of a machine failing among thousands of machines is common.
How does MapReduce handle machine failures?

Worker Failure
- The master sends heartbeat to each worker node.
- If a worker node fails, the master reschedules the tasks handled by the worker.

Master Failure
- The whole MapReduce job gets restarted through a different master.

End of Lecture 24
Same Example Problem: Map Reduce

Explain how the query will be executed in MapReduce

- SELECT a, max(b) as topb
- FROM R
- WHERE a > 0
- GROUP BY a

Specify the computation performed in the map and the reduce functions
Map

- Each map task
  - Scans a block of R
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```sql
SELECT a, max(b) as topb FROM R WHERE a > 0 GROUP BY a
```

- When each map task scans multiple relations, it needs to output something like
  ```sql
  key = a and value = ('R', b)
  ```
  which has the relation name ‘R’
Shuffle

• The MapReduce engine reshuffles the output of the map phase and groups it on the intermediate key, i.e. the attribute a

```sql
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```

• Note that the programmer has to write only the map and reduce functions, the shuffle phase is done by the MapReduce engine (although the programmer can rewrite the partition function)
Reduce

• Each reduce task
  • computes the aggregate value $\text{max}(b) = \text{topb}$ for each group (i.e. $a$) assigned to it (by calling the reduce function)
  • outputs the final results: $(a, \text{topb})$

A local combiner can be used to compute local max before data gets reshuffled (in the map tasks)

• Multiple aggregates can be output by the reduce phase like $\text{key} = a$ and $\text{value} = (\text{sum}(b), \text{min}(b))$ etc.

• Sometimes a second (third etc) level of Map-Reduce phase might be needed

```sql
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```
Any benefit of hash-partitioning for Map-Reduce?

- **For MapReduce**
  - Logically, MR won’t know that the data is hash-partitioned
  - MR treats map and reduce functions as black-boxes and does not perform any optimizations on them

- But, if a local combiner is used
  - Saves communication cost:
    - fewer tuples will be emitted by the map tasks
  - Saves computation cost in the reducers:
    - the reducers would have to do anything

```sql
SELECT a, max(b) as topb
FROM R
WHERE a > 0
GROUP BY a
```